CLAIMS

What is claimed is:

- 1 1. A hard disk drive, comprising:
- 2 a housing;
- 3 a spindle motor coupled to said housing;
- 4 a disk coupled to said spindle motor, said disk having
- 5 a middle diameter and an outer diameter;
- an actuator arm coupled to said housing;
- 7 a head coupled to said actuator arm;
- a voice coil motor coupled to said actuator arm;
- 9 a crash stop that makes contact with and impedes a
- 10 movement of said actuator arm; and,
- 11 a control circuit that controls said voice coil motor
- 12 to move said head from said middle diameter to said outer
- 13 diameter of said disk and then decelerate movement of said
- 14 head as said actuator arm.
- 1 2. The drive of claim 1, wherein said voice coil motor
- 2 remains energized for a time interval after said head
- 3 passes said outer diameter of said disk.

- 1 3. The drive of claim 1, further comprising a ramp
- 2 that receives said head.
- 1 4. The drive of claim 3, wherein said head is
- 2 decelerated while said head moves across said ramp.
- 1 5. The drive of claim 1, wherein movement of said head
- 2 across said disk is controlled by reading a Gray code of
- 3 said disk.
- 1 6. The drive of claim 1, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 7. The drive of claim 1, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 8. The drive of claim 1, wherein said head is
- 2 decelerated by applying a reverse current to said voice
- 3 coil motor.

- 9. The drive of claim 5, wherein movement of said head
- 2 beyond said outer diameter of said disk is controlled by
- 3 sensing a back emf of said voice coil motor.
- 1 10. The drive of claim 2, wherein movement of said
- 2 head across said disk is controlled by reading a Gray code
- 3 of said disk.
- 1 11. The drive of claim 2, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 12. The drive of claim 10, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 13. A hard disk drive, comprising:
- 2 a housing;
- 3 a spindle motor coupled to said housing;
- 4 a disk coupled to said spindle motor, said disk having
- 5 a middle diameter and an outer diameter;

- an actuator arm coupled to said housing;
- 7 a head coupled to said actuator arm;
- 8 a voice coil motor coupled to said actuator arm;
- 9 a crash stop that makes contact with and impedes a
- 10 movement of said actuator arm; and,
- 11 control means for controlling said voice coil motor to
- 12 move said head from said middle diameter to said outer
- 13 diameter of said disk and then decelerate movement of said
- 14 head as said actuator arm.
 - 1 14. The drive of claim 13, wherein said voice coil
 - 2 motor remains energized for a time interval after said head
 - 3 passes said outer diameter of said disk.
 - 1 15. The drive of claim 13, further comprising a ramp
 - 2 that receives said head.
 - 1 16. The drive of claim 15, wherein said head is
 - 2 decelerated while said head moves across said ramp.

- 1 17. The drive of claim 13, wherein movement of said
- 2 head across said disk is controlled by reading a Gray code
- 3 of said disk.
- 1 18. The drive of claim 13, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 19. The drive of claim 13, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 20. The drive of claim 13, wherein said head is
- 2 decelerated by applying a reverse current to said voice
- 3 coil motor.
- 1 21. The drive of claim 17, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.

- 1 22. The drive of claim 14, wherein movement of said
- 2 head across said disk is controlled by reading a Gray code
- 3 of said disk.
- 1 23. The drive of claim 14, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 24. The drive of claim 23, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 25. A hard disk drive, comprising:
- 2 a housing;
- 3 a spindle motor coupled to said housing;
- 4 a disk coupled to said spindle motor, said disk having
- 5 a middle diameter and an outer diameter;
- an actuator arm coupled to said housing;
- 7 a head coupled to said actuator arm;
- 8 a voice coil motor coupled to said actuator arm;

- 9 a crash stop that makes contact with and impedes a
- 10 movement of said actuator arm;
- a controller coupled to said voice coil motor; and,
- a memory that contains a program that causes said
- 13 controller to control said voice coil motor to move said
- 14 head from said middle diameter to said outer diameter of
- 15 said disk and then decelerate movement of said head.
- 1 26. The drive of claim 25, wherein said voice coil
- 2 motor remains energized for a time interval after said head
 - 3 passes said outer diameter of said disk.
 - 1 27. The drive of claim 25, further comprising a ramp
 - 2 that receives said head.
 - 1 28. The drive of claim 27, wherein said head is
 - 2 decelerated while said head moves across said ramp.
 - 1 29. The drive of claim 25, wherein movement of said
 - 2 head across said disk is controlled by reading a Gray code
 - 3 of said disk.

- 1 30. The drive of claim 25, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 31. The drive of claim 25, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 32. The drive of claim 25, wherein said head is
- 2 decelerated by applying a reverse current to said voice
- 3 coil motor.
- 1 33. The drive of claim 29, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 34. The drive of claim 26, wherein movement of said
- 2 head across said disk is controlled by reading a Gray code
- 3 of said disk.

- 1 35. The drive of claim 26, wherein movement of said
- 2 head across said disk is controlled by sensing a back emf
- 3 of said voice coil motor.
- 1 36. The drive of claim 34, wherein movement of said
- 2 head beyond said outer diameter of said disk is controlled
- 3 by sensing a back emf of said voice coil motor.
- 1 37. A method for moving a head of a hard disk drive
- 2 off of a disk, the head is coupled to an actuator arm,
- 3 comprising:
- 4 moving the head from a middle diameter of the disk to
- 5 an outer diameter of the disk; and,
- 6 decelerating the head as the actuator arm moves beyond
- 7 the outer diameter of the disk.
- 1 38. The method of claim 37, wherein the head is moved
- 2 with a voice coil motor and the voice coil motor remains
- 3 energized for a time interval after the head passes the
- 4 outer diameter of said disk.

- 1 39. The method of claim 37, wherein the head moves
- 2 onto a ramp.
- 1 40. The method of claim 39, wherein the head is
- 2 decelerated while the head moves across the ramp.
- 1 41. The method of claim 37, wherein movement of the
- 2 head across the disk is controlled by reading a Gray code
- 3 of the disk.
- 1 42. The method of claim 37, wherein movement of the
- 2 head across the disk is controlled by sensing a back emf of
- 3 the voice coil motor.
- 1 43. The method of claim 37, wherein movement of the
- 2 head beyond the outer diameter of the disk is controlled by
- 3 sensing a back emf of the voice coil motor.
- 1 44. The method of claim 37, wherein the head is
- 2 decelerated by applying a reverse current to the voice coil
- 3 motor.

- 1 45. The method of claim 41, wherein movement of the
- 2 head beyond the outer diameter of the disk is controlled by
- 3 sensing a back emf of the voice coil motor.
- 1 46. The method of claim 38, wherein movement of the
- 2 head across the disk is controlled by reading a Gray code
- 3 of the disk.
- 1 47. The method of claim 38, wherein movement of the
- 2 head across the disk is controlled by sensing a back emf of
- 3 the voice coil motor.
- 1 48. The method of claim 46, wherein movement of the
- 2 head beyond the outer diameter of the disk is controlled by
- 3 sensing a back emf of the voice coil motor.